Tutorial: Logic and Model Theory for Phonology

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Overview

Two things that are important to phonologists are:

Representations

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Features
Autosegments
Gestures
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...

Maps

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E.g., final devoicing: \begin{array}{l} \text{Leg., final devoicing:} \\ \text{lead}/\mapsto [\text{bet}] \\ \text{lead}/\mapsto [\text{akap}] \\ \text{lean}/\mapsto [\text{ben}] \\ \text{leazaz}/\mapsto [\text{azas}] \\ \vdots \end{array}
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- What is the difference between these two words?
 [aaa] and [aaaa]
- What is the difference between these two words? [barp] and [brap]
- What is the difference between these two words? [barp] and [parp]

■ What is the difference between these two words?

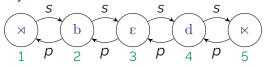
[aaa] and [aaaa] **elements** of the structure

■ What is the difference between these two words?

[barp] and [brap] **order** of elements

■ What is the difference between these two words?

[barp] and [parp] **properties** of the elements



- indices
- \blacksquare order functions p and s
- properties of the indices
- A model signature is a collection of functions and relations that are used to describe structures:

$$\{p,s,\textcolor{red}{S_1}...\textcolor{blue}{S_n}\}$$

■ A *model* is a structure in some signature:

$$\langle \mathbf{D}; \mathbf{p}, \mathbf{s}, \mathbf{S_1} ... \mathbf{S_n} \rangle$$

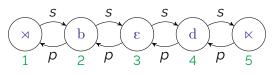
■ Model Signatures for Phonological Representations

Segment strings
Feature strings
Autosegmental structures
Syllable trees
Sign language structures
Articulatory structures

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 \begin{aligned} & \{\textbf{p}, \textbf{s}, \textbf{S}_1...\textbf{S}_n\} \\ & \{\textbf{p}, \textbf{s}, \textbf{F}_1...\textbf{F}_n\} \\ & \{\textbf{p}, \textbf{s}, \textbf{A}, \textbf{F}_1...\textbf{F}_n\} \\ & \{\textbf{p}, \textbf{s}, \textbf{parent}, \textbf{ons}, \textbf{nuc}, \textbf{cod}, \sigma\} \\ & \{\textbf{p}, \textbf{s}, \textbf{A}, \textbf{loc}, \textbf{L}, \textbf{M}, \textbf{H}_i, \textbf{P}_i\} \\ & \{\textbf{0}, \textbf{30}, \textbf{60}, \textbf{180}, \textbf{G}_1...\textbf{G}_n\} \end{aligned}
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Jardine (2017); Chandlee and Jardine (2019); Strother-Garcia (2019); Jardine et al. (2021); Oakden (2020); Rawski (2020); Chadwick (2021); Nelson (2022, 2023)

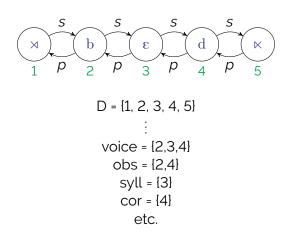
Segment strings



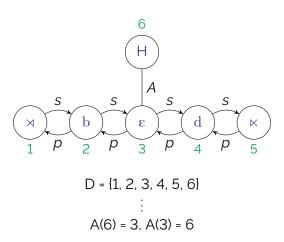
D = {1, 2, 3, 4, 5}
p(1) = 2, p(2) = 3, p(3) = 4, etc.
s(5) = 4, s(4) = 3, s(3) = 2, etc.
b = {2}

$$\epsilon$$
 = {3}
d = {4}

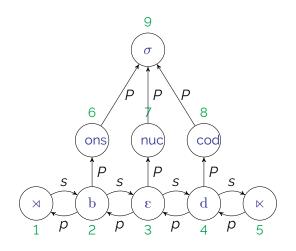
Feature strings



Autosegmental structures



Syllable trees



$$D = \{1, 2, 3, 4, 5, 6, 7, 8, 9\}$$

P(arent)(2) = 6, P(3) = 7, P(4) = 8, P(6) = 9, P(7) = 9, P(8) = 9

■ Why logic?

- Logic allows us to formalize our grammars/theories as sets of axioms that we can use to formally analyze and compare the types of structures that comply with a given theory.
- The computational complexity of logics are well known (McNaughton and Papert, 1971; Simon, 1975; Immerman, 1980; Rogers et al., 2013, et seq.)
- We can study the interaction of complexity and representation by changing the model while keeping the power of the logic fixed.
- Logical formalisms make for strong hypotheses about the complexity of phonology (Rogers et al., 2013; Heinz, 2018)

■ First-order logic describes truth conditions of structures

	Name	Meaning
X, y, Z R_1R_n F_1F_n	variables relations functions	Elements Order/Properties Order/Properties
	conjunction disjunction negation implication bi-direction existential quantifier universal quantifier	"And" "Or" "Not" "Ifthen" "Same" "There Exists" "For All"

- For any signature Σ , a Σ -formula is a logical formula where all the non-logical symbols are drawn from Σ .
- Suppose $\Sigma = \langle \mathbf{p}, \mathbf{s}, \mathbf{C}, \mathbf{V}, \rtimes, \ltimes \rangle$, which of the following are Σ -formulas?

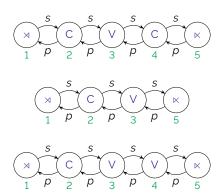
$$V(x) \wedge \ltimes (s(x))$$

 $G(x) \wedge \ltimes (s(x))$
 $G(x) \wedge \ltimes (A(x))$

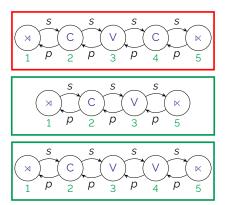
- For any signature Σ , a Σ -formula is a logical formula where all the non-logical symbols are drawn from Σ .
- Suppose $\Sigma = \langle \mathbf{p}, \mathbf{s}, \mathbf{C}, \mathbf{V}, \rtimes, \ltimes \rangle$, which of the following are Σ -formulas?

$$\begin{array}{ccc} \mathbf{V}(x) \wedge \ltimes (\mathbf{s}(x)) & \checkmark \\ \mathbf{G}(x) \wedge \ltimes (\mathbf{s}(x)) & \mathbf{X} \\ \mathbf{G}(x) \wedge \ltimes (\mathbf{A}(x)) & \mathbf{X} \end{array}$$

- If A is a structure built from Σ and φ is a Σ -formula, then we write $A \models \varphi$ if $\varphi(A)$ evaluates to true and say A satisfies (or *models*) φ . Otherwise, A does not satisfy/model φ .
- Which of the following structures satisfy $V(x) \land \ltimes (s(x))$?



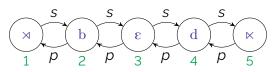
- If A is a structure built from Σ and φ is a Σ -formula, then we write $A \models \varphi$ if $\varphi(A)$ evaluates to true and say A satisfies (or *models*) φ . Otherwise, A does not satisfy/model φ .
- Which of the following structures satisfy $V(x) \land \ltimes (s(x))$?



Phonologists care about maps!

Defining new relations

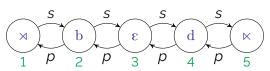
 $\langle \mathbf{D}; \mathbf{p}, \mathbf{s}, \mathbf{voi}, \mathbf{son}, \times, \times \rangle$



$$wdfinalobs(x) \equiv \neg son(x) \land \ltimes (s(x))$$

Defining new relations

 $\langle \mathbf{D}; \mathbf{p}, \mathbf{s}, \mathbf{voi}, \mathbf{son}, \times, \times \rangle$

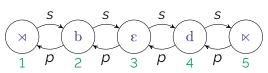


 $\mathbf{wdfinalobs}(x) \equiv \neg \mathbf{son}(x) \land \ltimes (s(x))$

	1	2	3	4	5
son(x)	\perp	\perp	Т	\perp	\perp
voi(x)	\perp	\top	\top	\top	\perp
wdfinalobs(x)	\perp	\perp	\perp	Τ	\perp

Defining new relations

 $\langle \mathbf{D}; \mathbf{p}, \mathbf{s}, \mathbf{voi}, \mathbf{son}, \times, \times \rangle$

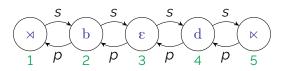


 $wdfinalobs(x) \equiv \neg son(x) \land \ltimes (s(x))$

	1	2	3	4	5
son(x) voi(x) wdfinalobs(x) ¬wdfinalobs(x)	\perp		T L		

Defining new structures

 $\langle \mathbf{D}; \mathbf{p}, \mathbf{s}, \mathbf{voi}, \mathbf{son}, \times, \ltimes \rangle$

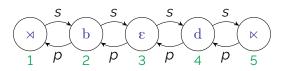


$$\mathbf{son}'(x) \equiv ...$$

 $\mathbf{voi}'(x) \equiv ...$

Defining new structures

 $\langle \mathbf{D}; \mathbf{p}, \mathbf{s}, \mathbf{voi}, \mathbf{son}, \times, \ltimes \rangle$

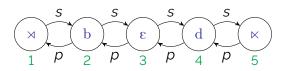


$$son'(x) \equiv son(x)$$

 $voi'(x) \equiv ...$

Defining new structures

 $\langle \mathbf{D}; \mathbf{p}, \mathbf{s}, \mathbf{voi}, \mathbf{son}, \times, \times \rangle$



$$\mathbf{son}'(x) \equiv \mathbf{son}(x)$$

 $\mathbf{voi}'(x) \equiv \mathbf{voi}(x) \land \neg \mathbf{wdfinalobs}(x)$

Defining new structures

$$\mathbf{son}'(x) \equiv \mathbf{son}(x)$$

 $\mathbf{voi}'(x) \equiv \mathbf{voi}(x) \land \neg \mathbf{wdfinalobs}(x)$

	×	b	ε	d	×
	1	2	3	4	5
son '(x) voi '(x)	⊥ ⊥	⊥ ⊤	T T	⊥ ⊥	

Defining new structures

$$son'(x) \equiv son(x)$$

 $voi'(x) \equiv voi(x) \land \neg wdfinalobs(x)$

Defining new structures

$$\mathbf{son}'(x) \equiv \mathbf{son}(x)$$

 $\mathbf{voi}'(x) \equiv \mathbf{voi}(x) \land \neg \mathbf{wdfinalobs}(x)$

	× 1	a 2	k 3	a 4	b 4	× 5
son'(x)	\perp	Т	\perp	Т	\perp	\perp
voi'(x)	\perp	Т	\perp	Т	\perp	\perp
	1′	2′	3′	4′	4′	5′
	\rtimes	\mathbf{a}	k	\mathbf{a}	p	\bowtie

Maps so defined are local (Chandlee and Lindell, forthcoming)

Recursive definitions

Iterative stress

Recursive definitions

Iterative, non-final stress (e.g., Pintupi)

$$\mathsf{stress}'(x) \equiv \sigma(x) \land \rtimes (p(x))$$

		σ 2						
stress'(x)	\perp	Т	\perp	\perp	\perp	1	\perp	\perp
	1′	2′	3′	4′	5′	6′	7′	8′
	\bowtie	$\acute{\sigma}$	σ	σ	σ	σ	σ	\bowtie

Recursive definitions

Iterative, non-final stress (e.g., Pintupi)

$$\mathsf{stress}'(x) \equiv \sigma(x) \land \big(\rtimes (\rho(x)) \lor \mathsf{stress}'(\rho(\rho(x))) \big)$$

x

$$\sigma$$
 σ
 σ

- Recursive, quantifier-free definitions are called boolean monadic recursive schemes (BMRS; Bhaskar et al., 2020; Chandlee and Jardine, 2021)
- Maps so defined are subsequential (Bhaskar et al., 2020), meaning that they are myopic (Wilson, 2003; Jardine, 2019)

Next Steps

- How do we learn logical grammars?
- What does a tertiary feature system look like in BMRS?
- BMRS captures elsewhere condition-type effects well. What about non-derived environment blocking?
- What is the status of intermediate representations?
- How does BMRS capture the typology of stress patterns?
- ... and many more!

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